

Programowanie współbieżne

LABORATORIUM - PROGRAMY, FORTRAN

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Programy I

```
circle.f90 - Prosty program.
```

```
! Circle
```

```
MODULE Circle_Operations
IMPLICIT NONE
CONTAINS
FUNCTION Area(radius)
REAL :: Area
REAL, INTENT(IN) :: Radius
Area = Radius**2 * 3.14159
END FUNCTION Area
FUNCTION Circumference(radius)
REAL :: Circumference
REAL, INTENT(IN) :: Radius
Circumference = Radius * 2 * 3.14159
END FUNCTION Circumference
END MODULE Circle_Operations
```

```
PROGRAM Circle
USE Circle_Operations
IMPLICIT NONE
REAL :: r=5.0
```

Programy II

```
PRINT *, "Area=", Area(r)
PRINT *, "Circumference=", Circumference(r)
END PROGRAM Circle
```

Programy III

oporniki.f90 - *Moduły. Interfejsy. Przykład dodawania oporów.*

```
!oporniki
```

```
MODULE oporniki
```

```
! dodawanie oporow
```

```
! a.rowno.b - rownolegle
```

```
! a.szereg.b - szeregowo
```

```
! Zadanie. DOPISAC czesc zwiazana z zamiana jednostek.
```

```
TYPE opornik
```

```
    REAL wartosc
```

```
    CHARACTER*4 miano
```

```
END TYPE opornik
```

```
INTERFACE OPERATOR (.SZEREG.)
```

```
    MODULE PROCEDURE SZ
```

```
END INTERFACE
```

```
INTERFACE OPERATOR (.ROWNO.)
```

```
    MODULE PROCEDURE RO
```

```
END INTERFACE
```

Programy IV

CONTAINS

```
FUNCTION SZ(a, b) RESULT(res)
  TYPE(opornik), INTENT(IN) :: a, b
  TYPE(opornik) res
  res%wartosc=a%wartosc+b%wartosc
  IF (a%miano==b%miano) THEN
    res%miano=a%miano
  ELSE
    res%miano="?"
  END IF
END FUNCTION SZ
FUNCTION RO(a, b) RESULT(res)
  TYPE(opornik), INTENT(IN) :: a, b
  TYPE(opornik) res
  REAL r
  r=1.0/a%wartosc+1.0/b%wartosc
  res%wartosc=1.0/r
  IF (a%miano==b%miano) THEN
    res%miano=a%miano
  ELSE
    res%miano="?"
  END IF
END FUNCTION RO
```

Programy V

```
END MODULE OPORNIKI
```

```
program d
```

```
  use oporniki
```

```
  TYPE(opornik) a, b, c
```

```
  a%wartosc=21.0; a%miano="om"
```

```
  b%wartosc=87.0; b%miano="om"
```

```
  c = a.ROWNO.b
```

```
  write(*,*) 'rowno : ', c%wartosc, c%miano
```

```
  c = a.SZEREG.b
```

```
  write(*,*) 'szereg: ', c%wartosc, c%miano
```

```
end program d
```

Programy VI

quaternions.f90 - *Kwaterniony.*

```
module Quaternions

  type, public :: quaternion
    real :: a, b, c, d
  end type quaternion

  intrinsic :: conjg

  private quat_mul_real, real_mul_quat, quat_mul_int, &
    int_mul_quat, quat_mul, quat_sub, quat_div, &
    quat_div_real, quat_div_int, quat_conjg

  interface operator (+)
    module procedure quat_add
  end interface

  interface operator (*)
    module procedure quat_mul_real
    module procedure real_mul_quat
```

Programy VII

```
    module procedure quat_mul_int
    module procedure int_mul_quat
    module procedure quat_mul
end interface
```

```
interface operator (-)
    module procedure quat_sub
end interface
```

```
interface operator (/)
    module procedure quat_div
!    module procedure quat_div_real
!    module procedure quat_div_int
end interface
```

```
interface conjg
    module procedure quat_conjg
end interface
```

contains

```
function quat_add(x,y) result (res)
    type(Quaternion), intent(in) :: x, y
    type(Quaternion) :: res
```


Programy VIII

```
    res % a = x % a + y % a
    res % b = x % b + y % b
    res % c = x % c + y % c
    res % d = x % d + y % d
end function quat_add

function quat_sub(x,y) result (res)
    type(quaternion), intent(in) :: x, y
    type(quaternion) :: res
    res % a = x % a - y % a
    res % b = x % b - y % b
    res % c = x % c - y % c
    res % d = x % d - y % d
end function quat_sub

function quat_conjg(x) result (res)
    type(quaternion), intent(in) :: x
    type(quaternion) :: res
    res % a = x % a
    res % b = -(x % b)
    res % c = -(x % c)
    res % d = -(x % d)
end function quat_conjg
```

Programy IX

```
function quat_mul_real(x,r) result (res)
  ! quat * real
  type(Quaternion), intent(in) :: x
  real, intent(in) :: r
  type(Quaternion) :: res
  res % a = x % a *r
  res % b = x % b *r
  res % c = x % c *r
  res % d = x % d *r
end function quat_mul_real
```

```
function real_mul_quat(r,x) result (res)
  ! real * quat
  type(Quaternion), intent(in) :: x
  real, intent(in) :: r
  type(Quaternion) :: res
  res = quat_mul_real(x,r)
end function real_mul_quat
```

```
function int_mul_quat(i,x) result (res)
  ! integer * quat
  type(Quaternion), intent(in) :: x
  integer, intent(in) :: i
  type(Quaternion) :: res
```

Programy X

```
    res = quat_mul_real(x,real(i))
end function int_mul_quat

function quat_mul_int(x,i) result (res)
    ! quat * integer
    type(Quaternion), intent(in) :: x
    integer, intent(in) :: i
    type(Quaternion) :: res
    res = int_mul_quat(i,x)
end function quat_mul_int

function quat_norm(q) result(res)
    type(Quaternion), intent(in) :: q
    real res
    real :: ap, bp, cp, dp
    ap = q % a
    bp = q % b
    cp = q % c
    dp = q % d
    res = sqrt(ap*ap+bp*bp+cp*cp+dp*dp)
end function quat_norm

function quat_div(x,y) result (res)
    type(Quaternion), intent(in) :: x, y
```

Programy XI

```
    type(quaternion) :: res
    real r
    r = 1.0/quat_norm(y)**2
    res = quat_mul_real(x,r)
end function quat_div

! MULTIPLICATION
function quat_mul(x,y) result (res)
    type(quaternion), intent(in) :: x, y
    type(quaternion) :: res
    real r
    res%a=0.; res%b=0.; res%c=0.; res%d=0.
end function quat_mul

subroutine quaternion_print(q)
    type(quaternion), intent(in) :: q
    real :: ap, bp, cp, dp
    ap = q % a
    bp = q % b
    cp = q % c
    dp = q % d
    print "(a1,4f12.6,a1)", "(,ap,bp,cp,dp,)"
end subroutine quaternion_print
```

Programy XII

```
end module Quaternions
!  
!-----  
! TEST  
Program Quater  
  use Quaternions  
  type(quaternion) :: u, v, w  
  u=quaternion(1,2,2,1)  
  v=quaternion(4,3,2,1)  
  w=u+v  
  call quaternion_print(w)  
  call quaternion_print(conjg(w))  
  call quaternion_print(w/w)  
  call quaternion_print(2.*w)  
  call quaternion_print(w*2.)  
  u = quaternion(1,0,0,0)  
  print *, quat_norm(u)  
end program Quater
```

Programy XIII

```
derivatives.f90 - Pierwsze i drugie pochodne.
```

```
!  
! Derivatives 1, 2 in 1-dim  
!  
module derivatives  
  
CONTAINS  
  
subroutine FirstDeriv_1d(npts, dx, u, u_x)  
  implicit none  
  integer, intent(in) :: npts  
  real, intent(in) :: dx  
  real, dimension(:), intent(in) :: u  
  real, dimension(:), intent(out) :: u_x  
  real two_invdx  
  integer i  
  two_invdx = 1d0/(2d0*dx)  
  ! central...  
  do i=2,npts-1  
    u_x(i)=(u(i+1)-u(i-1))*two_invdx  
  end do
```

Programy XIV

```
! forward...
u_x(1)=(-3.*u(1)+4.*u(2)-u(3))*two_invdx
! backward
u_x(npts)=(3.*u(npts)-4.*u(npts-1)+u(npts-2))*two_invdx
end subroutine FirstDeriv_1d

subroutine SecondDeriv_1d(npts, dx, u, u_xx)
  implicit none
  integer, intent(in) :: npts
  real, intent(in) :: dx
  real, dimension(:), intent(in) :: u
  real, dimension(:), intent(out) :: u_xx
  real inv_dx2
  integer i
  inv_dx2=1d0/(dx*dx)
  ! forward...
  u_xx(1)=(2.*u(1)-5.*u(2)+4.*u(3)-u(4))*inv_dx2
  ! central...
  do i=2,npts-1
    u_xx(i)=(u(i+1)-2.*u(i)+u(i-1))*inv_dx2
  end do
  ! backward
  u_xx(npts)=(2.*u(npts)-5.*u(npts-1)+4.*u(npts-2)-u(npts-3))*inv_dx2
end subroutine SecondDeriv_1d
```

Programy XV

```
end module derivatives
```


Programy XVI

TestDerivs.f90 - *Pochodne. Test.*

! Test of Derivatives routines

```
program TestDerivs
  use derivatives
  implicit none
  real func, func_x, func_xx
  integer, parameter :: levels=10 ! liczba poziomow do testowania
  real, parameter :: a=0d0 ! dolna granica przedzialu
  real, parameter :: b=1d0 ! gorna granica przedzialu
  real, dimension(:), allocatable :: u, u_x, u_xx
  integer i, j, npts, iall
  real dx, ux_error, uxx_error

  write(*,'(a)') " npts Error(1_Der) Error(2_Der)"
  do i=2,levels+1,1
    npts = 2**i ! liczba punktów rowna jest 2^level
    dx = 1d0/(npts-1) ! ustaw dx na podstawie liczby punktow

    ! rezerwuj pamiec, dynamicznie
    allocate(u (npts), stat=iall)
```

Programy XVII

```
allocate(u_x (npts), stat=iall)
allocate(u_xx(npts), stat=iall)

! function
do j=1,npts
    u(j) = func((j-1)*dx)
end do

call FirstDeriv_1d(npts, dx, u, u_x)
call SecondDeriv_1d(npts, dx, u, u_xx)

! error
ux_error = 0d0
uux_error = 0d0
do j=1,npts
    ux_error = ux_error + dx*(u_x (j)-func_x ((j-1)*dx))**2
    uux_error = uux_error + dx*(u_xx(j)-func_xx((j-1)*dx))**2
end do

write(*,'(i8, 2e20.9)') npts, sqrt(ux_error), sqrt(uux_error)

! zwolnij pamiec
deallocate(u, u_x, u_xx)
```

Programy XVIII

```
end do ! i

end program TestDerivs

real function func(x)
  func = x*x*x*x
end function func

real function func_x(x)
  func_x = 4d0*x*x*x
end function func_x

real function func_xx(x)
  func_xx = 12d0*x*x
end function func_xx

! wyniki obliczeń:
!
!      npts      Error(1_Der)      Error(2_Der)
!      4         0.448540793E+00    0.2004111100E+00
!      8         0.696229028E-01    0.242946550E+00
!     16         0.130890098E-01    0.367216199E-01
!     32         0.276197408E-02    0.616467539E-02
!     64         0.627306127E-03    0.110691791E-02
```

Programy XIX

!	128	0.148910393E-03	0.211078793E-03
!	256	0.362347450E-04	0.428963548E-04
!	512	0.893428971E-05	0.929152239E-05
!	1024	0.221800198E-05	0.212429174E-05
!	2048	0.552552792E-06	0.504635577E-06

Programy XX

hello.f90 - *Program demonstracyjny hello (Burkardt).*

```
program main
```

```
!*****8
!  
!! MAIN is the main program for HELLO.  
!  
! Discussion:  
!  
!   HELLO is a simple MPI test program.  
!  
!   Each process prints out a "Hello, world!" message.  
!  
!   The master process also prints out a short message.  
!  
! Licensing:  
!  
!   This code is distributed under the GNU LGPL license.  
!  
! Modified:  
!
```

Programy XXI

! 30 October 2008

!

! Author:

!

! John Burkardt

!

! Reference:

!

! William Gropp, Ewing Lusk, Anthony Skjellum,
! Using MPI: Portable Parallel Programming with the
! Message-Passing Interface,
! Second Edition,
! MIT Press, 1999,
! ISBN: 0262571323,
! LC: QA76.642.G76.

!

use mpi

!

! implicit none

!

integer error

integer id

integer p

real (kind = 8) wtime

Programy XXII

```
!  
! Initialize MPI.  
!  
call MPI_Init ( error )  
!  
! Get the number of processes.  
!  
call MPI_Comm_size ( MPI_COMM_WORLD, p, error )  
!  
! Get the individual process ID.  
!  
call MPI_Comm_rank ( MPI_COMM_WORLD, id, error )  
!  
! Print a message.  
!  
if ( id == 0 ) then  
  
    wtime = MPI_Wtime ( )  
  
    write ( *, '(a)' ) ' '  
    write ( *, '(a)' ) 'HELLO_WORLD - Master process:'  
    write ( *, '(a)' ) ' FORTRAN90 version'  
    write ( *, '(a)' ) ' '  
    write ( *, '(a)' ) ' An MPI test program.'
```

Programy XXIII

```
    write ( *, '(a)' ) ' '
    write ( *, '(a,i8)' ) ' The number of processes is ', p
    write ( *, '(a)' ) ' '

end if

write ( *, '(a)' ) ' '
write ( *, '(a,i8,a)' ) ' Process ', id, ' says "Hello, world!"'

if ( id == 0 ) then

    write ( *, '(a)' ) ' '
    write ( *, '(a)' ) 'HELLO_WORLD - Master process:'
    write ( *, '(a)' ) ' Normal end of execution: "Goodbye, world!".'

    wtime = MPI_Wtime ( ) - wtime
    write ( *, '(a)' ) ' '
    write ( *, '(a,g14.6,a)' ) ' Elapsed wall clock time = ', wtime, ' seconds

end if
!
! Shut down MPI.
!
call MPI_Finalize ( error )
```


Programy XXIV

```
    stop  
end
```

Programy XXV

FirstDeriv1dp.f90 - *Pochodne. Wersja równoległa*

```
!  
! Derivative 1, MPI  
!  
subroutine FirstDeriv1dp(npts, dx, u, u_x, mynode, totalnodes)  
  implicit none  
  integer, intent(in) :: npts, mynode, totalnodes  
  real*8, intent(in) :: dx  
  real*8, dimension(:), intent(in) :: u  
  real*8, dimension(:), intent(out) :: u_x  
  real*8 two_invdx  
  MPI_STATUS status  
  two_invdx = 1d0/(2d0*dx)  
  
  if(mynode == 0) then  
    ! forward...  
    u_x(1) = (-3.*u(1)+4.*u(2)-u(3))*two_invdx  
  end if  
  
  if(mynode == totalnodes) then  
    ! backward
```

Programy XXVI

```
    u_x(npts) = (3.*u(npts)-4.*u(npts-1)+u(npts-2))*two_invdX
end if

do i=2,npts-1
    ! central...
    u_x(i) = (u(i+1)-u(i-1))*two_invdX
end do

if (mynode == 0) then
    mpitemp = u(npts)
    call MPI_SEND(mpitemp, 1, MPI_DOUBLE, 1, 1, MPI_COM_WORLD)
    call MPI_RECV(mpitemp, 1, MPI_DOUBLE, 1, 1, MPI_COM_WORLD, status)
    u_x(npts) = (mpitemp-u(npts-1))*two_invdX
else if (mynode == totalnodes) then
    call MPI_RECV(mpitemp, 1, MPI_DOUBLE, mynode, 1, MPI_COM_WORLD, status)
    u_x(1) = (u(2)-mpitemp)*two_invdX
    mpitemp = u(1)
    call MPI_SEND(mpitemp, 1, MPI_DOUBLE, mynode, 1, MPI_COM_WORLD)
else
    call MPI_RECV(mpitemp, 1, MPI_DOUBLE, mynode, 1, MPI_COM_WORLD, status)
    u_x(1) = (u(2)-mpitemp)*two_invdX
    mpitemp = u(1)
    call MPI_SEND(mpitemp, 1, MPI_DOUBLE, mynode-1, 1, MPI_COM_WORLD)
    mpitemp = u(npts)
```

Programy XXVII

```
    call MPI_SEND(mpitemp, 1, MPI_DOUBLE, mynode+1, 1, MPI_COM_WORLD)
    call MPI_RECV(mpitemp, 1, MPI_DOUBLE, mynode+1, 1, MPI_COM_WORLD, status)
    u_x(npts) = (mpitemp-u(npts-1))*two_invdx
end if
end subroutine FirstDeriv1dp
```

Programy XXVIII

FirstDeriv1dpTest.f90 - *Pochodne. Test.*

```
! przykład użycia procedur SENDRECV i SEND-NDRECV_REPLACE
!  
integer mynode, totalnodes, mpierr  
integer datasize ! liczba jednostek danych send/recv  
integer process1, process2 ! rangi procesów wymieniających dane  
integer tag1, tag2 ! znacznik komunikatu  
real*8, dimension(:), allocatable :: buff, sendbuff, recvbuff  
MPI_status status ! zmienna przechowująca informacje o stanie  
  
call MPI_INIT( ierr )  
call MPI_COMM_SIZE(MPI_COM_WORLD, totalnodes, mpierr)  
call MPI_COMM_RANK(MPI_COM_WORLD, mynode, mpierr)  
  
! rezerwacja buforów danych, process1, process2  
allocate(sendbuff(datasize))  
allocate(recvbuff(datasize))  
allocate(buff(datasize))  
  
if (mynode == process1) then  
    ! dane w sendbuff są wysyłane do process2, odbierane od process2
```

Programy XXIX

```
! dane trafiają do bufora recvbuff
call MPI_SENDRECV(sendbuff, datasize, MPI_DOUBLE, process2, &
    tag1, recvbuff, datasize, MPI_DOUBLE, process2, &
    tag2, MPI_COMM_WORLD, status)
! wywołanie powoduje wymiane (swap) zawartosci bufora buff
! z process2
call MPI_SENDRECV_REPLACE(buff, datasize, MPI_DOUBLE, process2, &
    tag1, process2, tag2, MPI_COMM_WORLD, status)
end if

if (mynode == process2) then
! zawartosc sendbuff jest przekazana do procesu process1, a dane
! trzymane od procesu process1 sa umieszczane w buforze recvbuff
call MPI_SENDRECV(sendbuff, datasize, MPI_DOUBLE, process1, &
    tag2, recvbuff, datasize, MPI_DOUBLE, process1, &
    tag1, MPI_COMM_WORLD, status)
! wymiana danych buff z procesem process1
!
call MPI_SENDRECV_REPLACE(buff, datasize, MPI_DOUBLE, process1, &
    tag2, process1, tag1, MPI_COMM_WORLD, status)
end if

! process1 ma w swoim buforze recvbuff zawartosc bufora sendbuff
! procesu process1; process2 w swoim buforze recvbuff ma zawartosc
```

Programy XXX

- ! buforu sendbuff procesu process1; zawartosc buforow buff obu
- ! procesów została zamieniona

Programy XXXI

primes.f90 - *Poszukiwanie liczb pierwszych*

```
program primes
!
! Program zlicza liczby pierwsze w przedziale
! (kmin, kmax); podaje ich ilosc i czas zliczania
!
implicit none
integer, parameter :: kmin=1, kmax=1000
integer numberOfPrimes, countPrimes
real*4 startingTime, elapsedTime

! pomiar czasu
startingTime=secnds(0.0)

numberOfPrimes = countPrimes(kmin, kmax)
print *, numberOfPrimes

! czas wykonania
elapsedTime=secnds(startingTime) ! elapsed time
print *, "Time = ", elapsedTime
```


Programy XXXII

```
end program primes
```

```
function countPrimes(kmin, kmax) result(count)
  !
  ! procedura zlicza liczby pierwsze w przedziale
  ! (kmin, kmax) i zwraca ich liczbe
  !
  implicit none
  integer, intent(in) :: kmin, kmax
  integer number, count
  logical isPrime
  count = 0
  do number=kmin, kmax
    if (isPrime(number)) count = count + 1
  end do
end function countPrimes
```

```
function isPrime(number)
  !
  ! funkcja sprawdza, czy liczba jest pierwsza
  ! i zwraca .true. jesli jest lub .false.
  !
```

Programy XXXIII

```
logical isPrime
integer, intent(in) :: number
integer k, limit

limit = int(sqrt(float(number)))+1
isPrime = .true.
do k=2, limit
  if (mod(number,k) == 0) then
    isPrime = .false.
    return
  end if
end do
end function isPrime
```

Programy XXXIV

matvec.f90 - *Mnożenie macierzy przez wektor*

! MPI Tutorial
! Dr. Andrew C. Pineda, HPCERC/AHPCC
! Dr. Brian Smith, HPCERC/AHPCC
! The University of New Mexico
! November 17, 1997
! Last Revised: September 18, 1998

program matvec2

```
! Perform matrix vector product --  $Y = AX$   
! This is method two -- distribute A by block columns  
! and X in blocks (of rows) and the partial vector sum of Y is on  
! each processor.  
include 'mpif.h'  
integer, parameter :: dim1 = 80, dim2 = 10, dim3 = dim1*dim2  
integer ierr, rank, size, root, i, j  
integer sec_start, nano_start  
integer sec_curr, nano_curr  
integer sec_startup, nano_startup  
integer sec_comp, nano_comp  
integer sec_cleanup, nano_cleanup
```

Programy XXXV

```
real, dimension(dim1,dim1) :: a
real, dimension(dim1,dim2) :: apart
real, dimension(dim1) :: x, y, ypart
real, dimension(dim2) :: xpart
interface
  subroutine posix_timer(job_sec, job_nsec)
    integer job_sec, job_nsec
  end subroutine posix_timer
end interface
root = 0
call MPI_INIT( ierr )
call MPI_COMM_RANK( MPI_COMM_WORLD, rank, ierr )
call MPI_COMM_SIZE( MPI_COMM_WORLD, size, ierr )
print *, 'START process on processor ', rank
if( rank == root ) then
  call posix_timer(sec_start, nano_start)
  do i = 1, dim1
    x(i) = 1.0
    do j = 1, dim1
      a(j,i) = i + j
    enddo
  enddo
endif
! Distribute the 80x80 array A by columns as
```

Programy XXXVI

```
! 80x10 blocks stored in APART.
! Distribute the 80 dimensional
! array x in blocks of length 10
call MPI_SCATTER( a, dim3, MPI_REAL, apart, dim3, MPI_REAL, root,&
    & MPI_COMM_WORLD, ierr )
call MPI_SCATTER( x, dim2, MPI_REAL, xpart, dim2, MPI_REAL, root,&
    & MPI_COMM_WORLD, ierr )
if( rank == root ) then
    call posix_timer(sec_curr, nano_curr)
    sec_startup = sec_curr - sec_start
    nano_startup = nano_curr - nano_start
    sec_start = sec_curr
    nano_start = nano_curr
endif
do j = 1, dim1
    ypart(j) = 0.0
enddo
do i = 1, dim2
    do j = 1, dim1
        ypart(j) = ypart(j) + xpart(i)*apart(j,i)
    enddo
enddo
if( rank == root ) then
    call posix_timer(sec_curr, nano_curr)
```

Programy XXXVII

```
    sec_comp = sec_curr - sec_start
    nano_comp = nano_curr - nano_start
    sec_start = sec_curr
    nano_start = nano_curr
endif
call MPI_REDUCE( ypart, y, dim1, MPI_REAL, MPI_SUM, root, &
    MPI_COMM_WORLD, ierr )
if( rank == root ) then
    call posix_timer(sec_curr, nano_curr)
    sec_cleanup = sec_curr - sec_start
    nano_cleanup = nano_curr - nano_start
endif
print *, 'Finish processor ', rank
if( rank == root ) then
    print *, 'Matrix vector product, elements 10 and 60, are: ',&
        & y(10), y(60)
    print *, 'Startup execution times (sec, nano): ',&
        & sec_startup, nano_startup
    print *, 'Computation execution times (sec, nano): ',&
        & sec_comp, nano_comp
    print *, 'Cleanup execution times (sec, nano): ',&
        & sec_cleanup, nano_cleanup
endif
call MPI_FINALIZE( ierr )
```

Programy XXXVIII

end program matvec2

Programy XXXIX

gausselim.f90 - *Metoda Gaussa eliminacii*

```
! MPI Tutorial
! Dr. Andrew C. Pineda, HPCERC/AHPCC
! Dr. Brian Smith, HPCERC/AHPCC
! The University of New Mexico
! November 17, 1997
! Last Revised: September 18, 1998
```

```
module GaussianSolver
  implicit none
```

```
! The default value for the smallest pivot that will be accepted
! using the GaussianSolver subroutines. Pivots smaller than this
! threshold will cause premature termination of the linear equation
! solver and return false as the return value of the function.
real, parameter :: DEFAULT_SMALLEST_PIVOT = 1.0e-6
```

```
contains
```

```
! Use Gaussian elimination to calculate the solution to the linear
! system,  $A x = b$ . No partial pivoting is done. If the threshold
```


Programy XL

```
! argument is present, it is used as the smallest allowable pivot
! encountered in the computation; otherwise, DEFAULT_SMALLEST_PIVOT,
! defined in this module, is used as the default threshold. The status
! of the computation is a logical returned by the function indicating
! the existence of a unique solution (.true.), or the nonexistence of
! a unique solution or threshold passed (.false.).
! Note that this is an inappropriate method for some linear systems.
! In particular, the linear system,  $M x = b$ , where  $M = 10e-12 I$ , will
! cause this routine to fail due to the presence of small pivots.
! However, this system is perfectly conditioned, with solution  $x = b$ .
function gaussianElimination( A, b, x, threshold )
  implicit none
  logical gaussianElimination
  real, dimension( :, : ), intent( in ) :: A ! Assume the shape of A.
  real, dimension( : ), intent( in ) :: b ! Assume the shape of b.
  real, dimension( : ), intent( out ) :: x ! Assume the shape of x.
  ! The optional attribute specifies that the indicated argument 40
  ! is not required to be present in a call to the function. The
  ! presence of optional arguments, such as threshold, may be checked
  ! using the intrinsic logical function, present (see below).
  real, optional, intent( in ) :: threshold
  integer i, j ! Local index variables.
  integer N ! Order of the linear system.
  real m ! Multiplier.
```

Programy XLI

```
real :: smallestPivot = DEFAULT_SMALLEST_PIVOT
! Pointers to the appropriate rows of the matrix during the elimination.
real, dimension( : ), pointer :: pivotRow
real, dimension( : ), pointer :: currentRow
! Copies of the input arguments. These copies are modified during
! the computation. The target attribute is used to indicate that
! the specified variable may be the target of a pointer. Rows of
! ACopy are targets of pivotRow and currentRow, defined above.
real, dimension( size( A, 1 ), size( A, 2 ) ), target :: ACopy
real, dimension( size( b ) ) :: bCopy
!
! Status of the computation. The return value of the function.
!
logical successful

!
! Change the smallestPivot if the threshold argument was included.
!
if ( present( threshold ) ) smallestPivot = abs( threshold )
!
! Setup the order of the system by using the intrinsic function size.
! size returns the number of elements in the specified dimension of
! an array or the total number of elements if the dimension is not
! specified. Also assume that a unique solution exists initially.
```

Programy XLII

```
!  
N = size( b )  
ACopy = A  
bCopy = b  
successful = .true.  
!  
! Begin the Gaussian elimination algorithm. Note the use of array  
! sections in the following loops. These eliminate the need for  
! many do loops that are common in Fortran 77 code. Pointers are  
! also used below and enhance the readability of the elimination  
! process. Begin with the first row.  
!  
i = 1  
! Reduce the system to upper triangular.  
do while ( ( successful ) .and. ( i < N ) )  
  !  
  ! The following statement is called pointer assignment and uses  
  ! the pointer assignment operator '=>'. This causes pivotRow  
  ! to be an alias for the ith row of ACopy. Note that this does  
  ! not cause any movement of data.  
  ! Assign the pivot row.  
  !  
  pivotRow => ACopy( i, : )  
  !
```

Programy XLIII

```
! Verify that the current pivot is not smaller than smallestPivot.
!
successful = abs( pivotRow( i ) ) >= smallestPivot
if ( successful ) then
    !
    ! Eliminate the entries in the pivot column below the pivot row.
    !
    do j = i+1, N
        ! Assign the current row.
        currentRow => ACopy( j, : )
        ! Calculate the multiplier.
        m = currentRow( i ) / pivotRow( i )
        ! Perform the elimination step on currentRow and right
        ! hand side, bCopy.
        currentRow = currentRow - m * pivotRow
        bCopy( j ) = bCopy( j ) - m * bCopy( i )
    enddo
endif
! Move to the next row.
i = i + 1
end do
! Check the last pivot.
pivotRow => ACopy( N, : )
if ( successful ) successful = abs( pivotRow( N ) ) >= smallestPivot
```

Programy XLIV

```
if ( successful ) then
    do i = N, 2, -1 ! Backward substitution.
        ! Determine the ith unknown, x( i ).
        x( i ) = bCopy( i ) / ACopy( i, i )
        ! Substitute the now known value of x( i ), reducing the order of
        ! the system by 1.
        bCopy = bCopy - x( i ) * ACopy( :, i )
    enddo
endif
! Determine the value of x( 1 ) as a special case.
if ( successful ) x( 1 ) = bCopy( 1 ) / ACopy( 1, 1 )
! Prepare the return value of the function.
gaussianElimination = successful
end function gaussianElimination

! Output A in Matlab format, using name in the Matlab assignment statement.
subroutine printMatrix( A, name )
    implicit none
    real, dimension( :, : ) :: A ! Assume the shape of A.
    character name ! Name for use in assignment, ie, name =
    ! .....
    integer n, m, i, j
    n = size( A, 1 )
    m = size( A, 2 )
```

Programy XLV

```
write( *, fmt="(a1,a5)", advance = "no" ) name, ' = [ '
! Output the matrix, except for the last row, which needs no ';'
do i = 1, n-1
  ! Output current row.
  do j = 1, m-1
    write( *, fmt="(f10.6,a2)", advance = "no" ) A( i, j ), ', '
  enddo
  ! Output last element in row and end current row.
  write( *, fmt="(f10.6,a1)" ) A( i, m ), ';'
enddo
! Output the last row.
do j = 1, m-1
  write( *, fmt="(f10.6,a2)", advance = "no" ) A( i, j ), ', '
enddo
! Output last element in row and end.
write( *, fmt="(f10.6,a1)" ) A( i, m ), ']'
end subroutine printMatrix

! Output b in Matlab format, using name in the Matlab assignment statement.
subroutine printVector( b, name )
  implicit none
  real, dimension( : ) :: b ! Assume the shape of b.
  character name ! Name for use in assignment, ie, name = .....
  integer n, i
```

Programy XLVI

```
n = size( b )
write( *, fmt="(a1,a5)", advance = "no" ) name, ' = [ '
do i = 1, n-1
    write( *, fmt = "(f10.6,a2)", advance = "no" ) b( i ), ', '
enddo
write( *, fmt = "(f10.6,a2)" ) b( n ), ']'
end subroutine printVector
end module GaussianSolver
```

! A program to solve linear systems using the GaussianSolver module.

```
program SolveLinearSystem
```

```
! Include the module for the various linear solvers.
```

```
use GaussianSolver
```

```
implicit none
```

```
integer, parameter :: N = 5 ! Order of the linear system.
```

```
real, parameter :: TOO_SMALL = 1.0e-7 ! Threshold for pivots.
```

```
! Declare the necessary arrays and vectors to solve the linear system
```

```
!  $Ax = b$ .
```

```
real, dimension( N, N ) :: A ! Coefficient matrix.
```

```
real, dimension( N ) :: x, b ! Vector of unknowns, and right hand side.
```

```
real, dimension( N, N ) :: LU ! Matrix for LU factorization of A.
```

```
logical successful ! Status of computations.
```

Programy XLVII

```
! The intrinsic subroutine, random_number, fills a real array or scalar,  
! with uniformly distributed random variates in the interval [0,1).  
call random_number( A ) ! Initialize the coefficient matrix.  
call random_number( b ) ! Initialize the right-hand side.
```

```
! Output the matrix in Matlab format for ease of checking the solution.  
call printMatrix( A, 'A' )  
call printVector( b, 'b')
```

```
! Use Gaussian elimination to calculate the solution of the linear system.  
! The call below uses the default threshold specified in the  
! GaussianSolver module by omitting the optional argument.
```

```
successful = gaussianElimination( A, b, x )  
print *, '=====  
print *, 'Gaussian Elimination:'  
print *, '-----'  
if ( successful ) then  
    call printVector( x, 'x' )  
    print *, 'Infinity Norm of Difference = ', &  
            maxval( abs ( matmul( A, x ) - b ) )  
else  
    print *, 'No unique solution or threshold passed.'  
endif
```


Programy XLVIII

```
end program SolveLinearSystem
```

Programy XLIX

m-w.f90 - *Model master-slave*

```
PROGRAM MASTER_WORKER
  USE MPI
  INTEGER istatus(MPI_STATUS_SIZE)
  PARAMETER (njobmx=124)
  !
  CALL MPI_INIT(ierr)
  CALL MPI_COMM_SIZE(MPI_COMM_WORLD,nprocs,ierr)
  CALL MPI_COMM_RANK(MPI_COMM_WORLD,myrank,ierr)

  !===== MASTER
  !
  ! The master recives the masages from workers and if some worker
  ! is idle it sends to it a job number. the worker realizes this
  ! job and sends the message again to the master. If all jobs are
  ! processed then if the worker has finished the master sends the
  ! term signal (job=-1) to the worker and the worker exits.
  !
  IF (myrank == 0) THEN
```

Programy L

```
itag=1
DO njob=1,njobmx
  CALL MPI_RECV(iwk, 1, MPI_INTEGER, MPI_ANY_SOURCE, &
    itag, MPI_COMM_WORLD, istatus, ierr)
  idest=istatus(MPI_SOURCE)
  CALL MPI_SEND(njob, 1, MPI_INTEGER, idest, &
    itag, MPI_COMM_WORLD, ierr)
END DO
```

```
DO i=1,nprocs-1
  CALL MPI_RECV(iwk, 1, MPI_INTEGER, MPI_ANY_SOURCE, &
    itag, MPI_COMM_WORLD, istatus, ierr)
  idest=istatus(MPI_SOURCE)
  CALL MPI_SEND(-1, 1, MPI_INTEGER, idest, &
    itag, MPI_COMM_WORLD, ierr)
END DO
```

ELSE

```
!===== WORKER
```

```
!
```

```
! The worker sends the signal to the master that it is idle.
```

```
! if there are jobs to process then the master sends to the
```

```
! worker the job number (njob) and the worker processes the job.
```

Programy LI

! If there are no other jobs the number njob sent to the worker
! is equal to -1 and after receiving it the worker exits.

```
itag=1
```

```
iwk=0
```

```
DO
```

```
CALL MPI_SEND(iwk, 1, MPI_INTEGER, 0, &  
itag, MPI_COMM_WORLD, ierr)
```

```
CALL MPI_RECV(njob, 1, MPI_INTEGER, 0, &  
itag, MPI_COMM_WORLD, istatus, ierr)
```

```
IF (njob == -1) EXIT
```

```
CALL DOSOMETHING(njob)
```

```
END DO
```

```
!
```

```
CALL MPI_FINALIZE(ierr)
```

```
END IF
```

```
END PROGRAM MASTER
```

Programy LII

```
SUBROUTINE DOSOMETHING(JOB)
  !
  ! MAIN JOB
  !
END SUBROUTINE DOSOMETHING
```

Programy LIII

rwalk.f90 - *Random walk, Monte Carlo method; wersja sekwencyjna*

! RS6000 SP: Practical MPI programming

PROGRAM randomwalk

PARAMETER (n = 10000)

INTEGER itotal(0:9)

REAL seed

pi = 3.1415926

DO i = 0, 9

 itotal(i) = 0

END DO

! Uwaga: zalezy od kompilatora

! tutaj: gfortran

iseed = 5

CALL srand(iseed)

DO i = 1, n

 x = 0.0

 y = 0.0

 DO istep = 1, 10

 angle = 2.0 * pi * rand()

 x = x + cos(angle)

Programy LIV

```
        y = y + sin(angle)
    END DO
    itemp = sqrt(x*x + y*y)
    itotal(itemp) = itotal(itemp) + 1
END DO
PRINT *, "total =", itotal
END PROGRAM randomwalk
```

Programy LV

rwalk-p.f90 - *Random walk, Monte Carlo method; w. równoległa*

! RS6000 SP: Practical MPI programming

PROGRAM randomwalk_p

INCLUDE "mpif.h"

PARAMETER (n = 100000)

INTEGER itotal(0:9), iitotal(0:9)

REAL seed

CALL MPI_INIT(ierr)

CALL MPI_COMM_SIZE(MPI_COMM_WORLD, nprocs, ierr)

CALL MPI_COMM_RANK(MPI_COMM_WORLD, myrank, ierr)

CALL para_range(1, n, nprocs, myrank, ista, iend)

pi = 3.1415926

DO i = 0, 9

itotal(i) = 0

END DO

! Uwaga: zalezy od kompilatora

Programy LVI

```
! tutaj: gfortran
seed = 5 + myrank
CALL srand(seed)
DO i = ista, iend
  x = 0.0
  y = 0.0
  DO istep = 1, 10
    angle = 2.0 * pi * rand()
    x = x + cos(angle)
    y = y + sin(angle)
  END DO
  itemp = sqrt(x**2 + y**2)
  itotal(itemp) = itotal(itemp) + 1
END DO

CALL MPI_REDUCE(itotal, iitotal, 10, MPI_INTEGER, MPI_SUM, 0, &
  MPI_COMM_WORLD, ierr)

PRINT *, "total =", iitotal

CALL MPI_FINALIZE(ierr)
END
```

Programy LVII

```
SUBROUTINE para_range(n1, n2, nprocs, irank, ista, iend)
  iwork1 = (n2 - n1 + 1) / nprocs
  iwork2 = MOD(n2 - n1 + 1, nprocs)
  ista = irank * iwork1 + n1 + MIN(irank, iwork2)
  iend = ista + iwork1 - 1
  IF (iwork2 > irank) iend = iend + 1
END SUBROUTINE para_range
```

Programy LVIII

BlasEx.f - Przykłady użycia biblioteki BLAS

Example

```
implicit real*8 (a-h,o-z)
parameter(maxn=200,m=80,k=maxn+1)
parameter(zero=0.0d0,one=1.0d0)
real*8 a(k,maxn),aa(k,maxn),x(k,m),b(k,m)
integer ip(maxn)
```

```
C =====
C Define the matrix
C =====
n=maxn
call inita(a,k,n)
do i=1,n
  do j=1,n
    aa(j,i)=a(j,i)
  end do
end do
C =====
C LU decomposition
C =====
c all dgetrf(n,n,a,k,ip,info)
```

Programy LIX

```
C =====
C   Defeine the vectors
C =====
C   do jm=1,m
C       do jn=1,n
C           x(jn,jm)=jn+jm
C       end do
C   end do
C   call dgemm('N','N',n,m,n,one,aa,k,x,k,zero,b,k)
C =====
C   Solution
C =====
C   call dgetrs('N',n,m,a,k,ip,b,k,info)
C   if(info.ne.0) then
C       write(6,*) 'error in dgetrs info = ',info
C       stop
C   end if
C =====
C   Check result
C =====
C   call check(a, b, k, n, m)

end
```

Programy LX

```
wsad1 - ...
```

```
#!/bin/sh
# plik wsad1
# praca w srodowisku Xeon, gondor; plik PBS
# obliczenia sekwencyjne
#PBS -S /bin/sh
#PBS -N nazwa
#PBS -l walltime=10:00:00
#PBS -l mem=4GB
#PBS -l ncpus=1
#
export OMP_NUM_THREADS=1
cd /home/uzytkownik/katalog
./prog < input > output
```

Programy LXI

```
wsad2 - ...
```

```
#!/bin/sh
# plik wsad2
# OpenMP lub BLAS3 z MKL - xeony
#
#PBS -S /bin/sh
#PBS -N ichox
#PBS -l walltime=10:00:00
#PBS -l mem=4GB
#PBS -l ncpus=X
#PBS -l nodes=1:ppn=X
#
export OMP_NUM_THREADS=X
cd /home/uzytownik/katalog
./prog < input > output
```

Programy LXII

```
wsad3 - ...
```

```
#!/bin/sh
# plik wsad3
# MPI - xeony
#
#PBS -S /bin/sh
#PBS -N ntrs
#PBS -l walltime=10:00:00
#PBS -l mem=10GB
#PBS -l nodes=2:ppn=8
#
cd /home/uzytkownik/katalog
source /opt/bin/intel64
export OMP_NUM_THREADS=1
mpirun -genv I_MPI_DEVICE ssm -ppn 8 -n 16 ./ntrs < input > output
```

Programy LXIII

```
wsad4 - ...
```

```
#!/bin/sh
# plik wsad4
# wezel ROHAN, rohan
#
#PBS -S /bin/sh
#PBS -N testowe
#PBS -l mem=1GB
#PBS -l nodes=x:itanium:ppn=2
source /opt/bin/ia64
```


Programy LXIV

Makefile.ex - *Przykładowy plik Makefile*

```
PROG2    = ntrs
FILES2   = blt.f loca.f
LDLIBS   = -L/opt/intel/mkl/10.2.2.025/lib/em64t -lmkl_scalapack_lp64 \
          -lmkl_blacs_intelmpi_lp64 -lmkl_intel_thread -lmkl_intel_lp64 \
          -lmkl_core -liomp5 -lpthread
OPTFLG   = -O3 -xT -openmp -parallel
all:
    mpiifort $(OPTFLG) -o $(PROG2) $(FILES2) $(LDLIBS)
clean:
    rm -f core *.o
```

Programy LXV